



BENHA UNIVERSITY  
FACULTY OF ENGINEERING AT SHOUBRA

**ECE-312**  
**Electronic Circuits (A)**

Lecture # 7  
BJT Low Frequency Response

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كلية الهندسة بشبرا

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# Agenda

Low Frequency Analysis- Bode Plot

Low Frequency Response – BJT Amplifier with  $R_L$

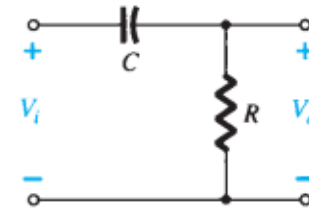
Impact of  $R_S$  on the BJT Low Frequency Response

# LOW FREQUENCY ANALYSIS- BODE PLOT



# Defining the Low Cutoff Frequency

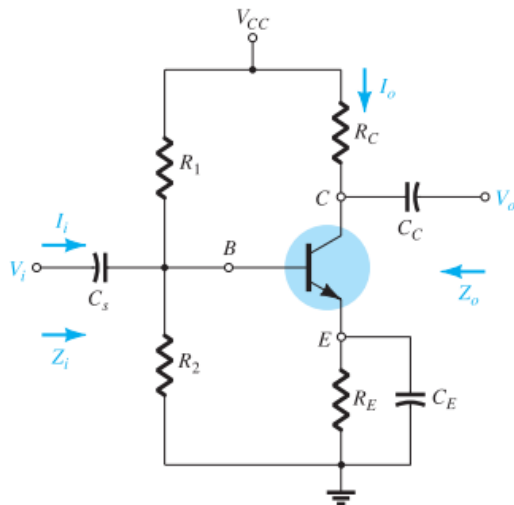
- In the low-frequency region of the single-stage BJT or FET amplifier, it is the RC combinations formed by the network capacitors  $C_C$ ,  $C_E$ , and  $C_S$  and the network resistive parameters that determine the cutoff frequencies



**FIG. 9.14**

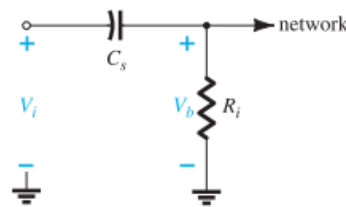
*RC combination that will define a low-cutoff frequency.*

- Voltage-Divider Bias Config.



**FIG. 9.15**

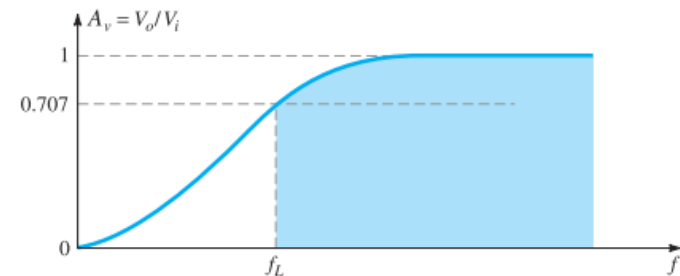
*Voltage-divider bias configuration.*



**FIG. 9.16**

*Equivalent input circuit for the network of Fig. 9.15.*

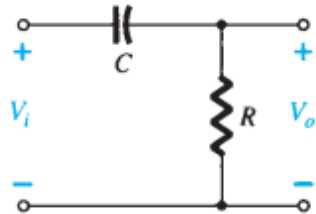
$$Z_i = R_i = R_1 \parallel R_2 \parallel \beta r_e$$



**FIG. 9.19**

*Low-frequency response for the RC circuit of Fig. 9.14.*

# Defining The Low Cutoff Frequency ..



$$V_o = \frac{RV_i}{R + X_C}$$

The magnitude of  $V_o$  is

$$V_o = \frac{RV_i}{\sqrt{R^2 + X_C^2}}$$

For the special case where  $X_C = R$ ,

$$V_o = \frac{RV_i}{\sqrt{R^2 + X_C^2}} = \frac{RV_i}{\sqrt{R^2 + R^2}} = \frac{RV_i}{\sqrt{2R^2}} = \frac{RV_i}{\sqrt{2}R} = \frac{1}{\sqrt{2}}V_i$$

$$|A_v| = \frac{V_o}{V_i} = \frac{1}{\sqrt{2}} = 0.707|_{X_C=R}$$

$$X_C = \frac{1}{2\pi f_L C} = R$$

$$f_L = \frac{1}{2\pi RC}$$

$$G_v = 20 \log_{10} A_v = 20 \log_{10} \frac{1}{\sqrt{2}} = -3 \text{ dB}$$

$$A_v = V_o/V_i = 1 \text{ or } V_o = V_i \text{ (the maximum value),}$$

$$G_v = 20 \log_{10} 1 = 20(0) = 0 \text{ dB}$$

$$A_v = \frac{V_o}{V_i} = \frac{R}{R - jX_C} = \frac{1}{1 - j(X_C/R)} = \frac{1}{1 - j(1/\omega CR)} = \frac{1}{1 - j(1/2\pi fCR)}$$

$$f_L = \frac{1}{2\pi RC}$$

$$A_v = \frac{1}{1 - j(f_L/f)}$$

In the magnitude and phase form,

$$A_v = \frac{V_o}{V_i} = \frac{1}{\underbrace{\sqrt{1 + (f_L/f)^2}}_{\text{magnitude of } A_v}} \underbrace{\angle \tan^{-1}(f_L/f)}_{\text{phase } \angle \text{ by which } V_o \text{ leads } V_i}$$

when  $f = f_L$ ,

$$|A_v| = \frac{1}{\sqrt{1 + (1)^2}} = \frac{1}{\sqrt{2}} = 0.707 \Rightarrow -3 \text{ dB}$$

$$A_{v(\text{dB})} = 20 \log_{10} \frac{1}{\sqrt{1 + (f_L/f)^2}}$$



# Bode Plot

$$A_{v(\text{dB})} = 20 \log_{10} \frac{1}{\sqrt{1 + (f_L/f)^2}}$$

$$\begin{aligned} A_{v(\text{dB})} &= -20 \log_{10} \left[ 1 + \left( \frac{f_L}{f} \right)^2 \right]^{1/2} \\ &= -\left(\frac{1}{2}\right)(20) \log_{10} \left[ 1 + \left( \frac{f_L}{f} \right)^2 \right] \\ &= -10 \log_{10} \left[ 1 + \left( \frac{f_L}{f} \right)^2 \right] \end{aligned}$$

For frequencies where  $f \ll f_L$  or  $(f_L/f)^2 \gg 1$ ,

$$A_{v(\text{dB})} = -10 \log_{10} \left( \frac{f_L}{f} \right)^2$$

$$A_{v(\text{dB})} = -20 \log_{10} \frac{f_L}{f} \quad f \ll f_L$$

At  $f = f_L$ :  $\frac{f_L}{f} = 1$  and  $-20 \log_{10} 1 = 0$  dB

At  $f = \frac{1}{2}f_L$ :  $\frac{f_L}{f} = 2$  and  $-20 \log_{10} 2 \cong -6$  dB

At  $f = \frac{1}{4}f_L$ :  $\frac{f_L}{f} = 4$  and  $-20 \log_{10} 4 \cong -12$  dB

At  $f = \frac{1}{10}f_L$ :  $\frac{f_L}{f} = 10$  and  $-20 \log_{10} 10 = -20$  dB

- The piecewise linear plot of the asymptotes and associated breakpoints is called a Bode plot of the magnitude versus frequency.

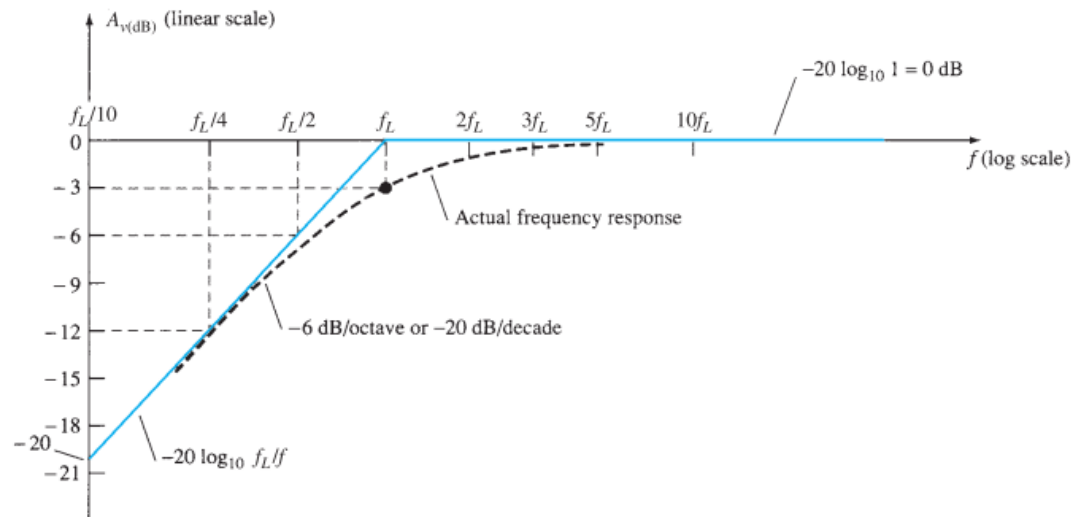


FIG. 9.20

Bode plot for the low-frequency region.



# Bode Plot..

- A change in frequency by a factor of two, equivalent to **one octave**, results in a 6-dB change in the ratio, as shown by the change in gain from  $f_L/2$  to  $f_L$ .
- For a 10:1 change in frequency, equivalent to **one decade**, there is a 20-dB change in the ratio, as demonstrated between the frequencies of  $f_L/10$  and  $f_L$ .
- Phase Angle:

$$A_{v(\text{dB})} = 20 \log_{10} \frac{V_o}{V_i}$$

$$\frac{A_{v(\text{dB})}}{20} = \log_{10} \frac{V_o}{V_i}$$

$$A_v = \frac{V_o}{V_i} = 10^{A_{v(\text{dB})}/20}$$

$$\theta = \tan^{-1} \frac{f_L}{f}$$

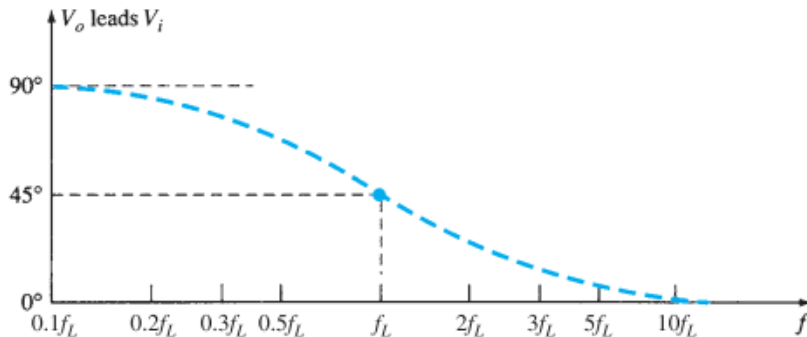


FIG. 9.22

Phase response for the RC circuit of Fig. 9.14.

For frequencies  $f \ll f_L$ ,

$$\theta = \tan^{-1} \frac{f_L}{f} \rightarrow 90^\circ$$

For instance, if  $f_L = 100f$ ,

$$\theta = \tan^{-1} \frac{f_L}{f} = \tan^{-1}(100) = 89.4^\circ$$

For  $f = f_L$ ,

$$\theta = \tan^{-1} \frac{f_L}{f} = \tan^{-1} 1 = 45^\circ$$

For  $f \gg f_L$ ,

$$\theta = \tan^{-1} \frac{f_L}{f} \rightarrow 0^\circ$$

For instance, if  $f = 100f_L$ ,

$$\theta = \tan^{-1} \frac{f_L}{f} = \tan^{-1} 0.01 = 0.573^\circ$$



# Example

**EXAMPLE 9.10** For the network of Fig. 9.23:

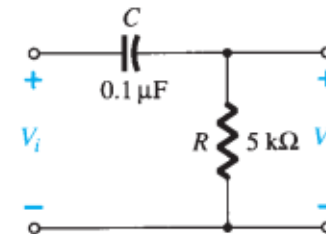
- Determine the break frequency.
- Sketch the asymptotes and locate the  $-3$ -dB point.
- Sketch the frequency response curve.
- Find the gain at  $A_{v(\text{dB})} = -6$  dB.

**Solution:**

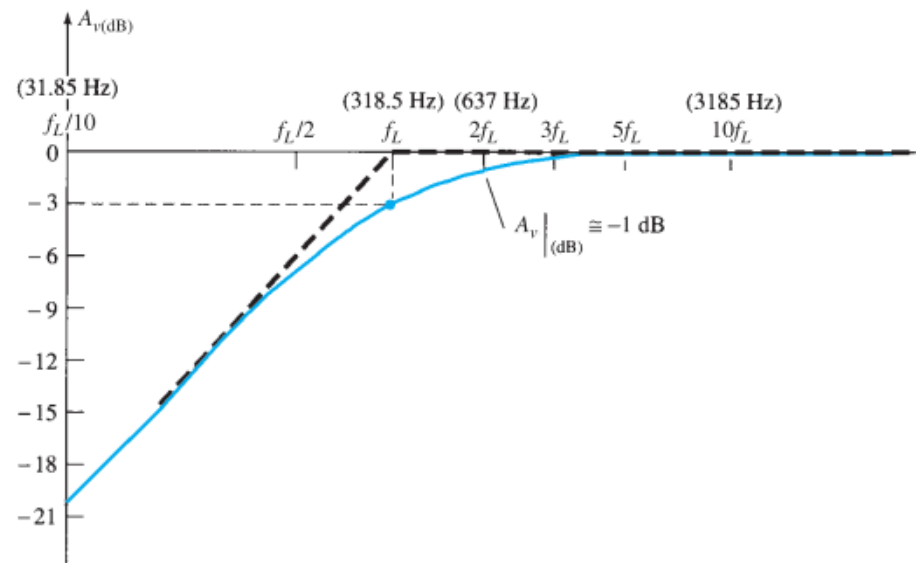
$$\text{a. } f_L = \frac{1}{2\pi RC} = \frac{1}{(6.28)(5 \times 10^3 \Omega)(0.1 \times 10^{-6} \text{ F})} \\ \cong \mathbf{318.5 \text{ Hz}}$$

b. and c. See Fig. 9.24.

$$\text{d. Eq. (9.27): } A_v = \frac{V_o}{V_i} = 10^{A_{v(\text{dB})}/20} \\ = 10^{(-6/20)} = 10^{-0.3} = 0.501 \\ \text{and } V_o = 0.501 V_i \text{ or approximately } 50\% \text{ of } V_i.$$



**FIG. 9.23**  
Example 9.10.



**FIG. 9.24**

Frequency response for the RC circuit of Fig. 9.23.



# LOW FREQUENCY RESPONSE – BJT AMPLIFIER WITH $R_L$



( 9 )

# Loaded BJT Amplifier

In the voltage-divider ct.  
 → the capacitors  $C_s$ ,  $C_C$ ,  
 and  $C_E$  will determine the  
 low-frequency response.

$$f_L = \min(f_{L_s}, f_{L_C}, f_{L_E})$$

→  $C_s$ :

$$V_b = \frac{R_i V_i}{R_i - jX_{C_s}}$$

$$f_{L_s} = \frac{1}{2\pi R_i C_s} \quad R_i = R_1 \parallel R_2 \parallel \beta r_e$$

$$A_v = \frac{V_o}{V_i} = \frac{1}{1 - j(f_{L_s}/f)}$$

→  $C_C$ :

$$f_{L_C} = \frac{1}{2\pi(R_o + R_L)C_C}$$

$$R_o = R_C \parallel r_o$$

→  $C_E$ :

$$f_{L_E} = \frac{1}{2\pi R_e C_E}$$

$$R_e = R_E \parallel \left( \frac{R_1 \parallel R_2}{\beta} + r_e \right)$$

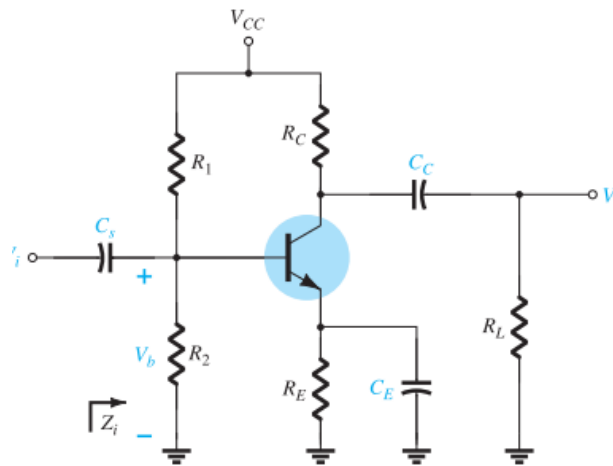


FIG. 9.25

Loaded BJT amplifier with capacitors that affect the low-frequency response.

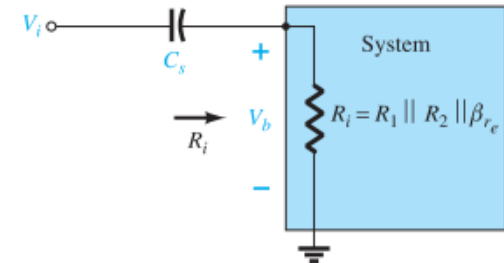


FIG. 9.26

Determining the effect of  $C_s$  on the low-frequency response.

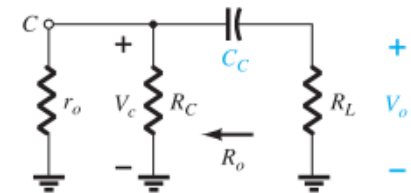


FIG. 9.28

Localized ac equivalent for  $C_C$  with  $V_i = 0$  V.

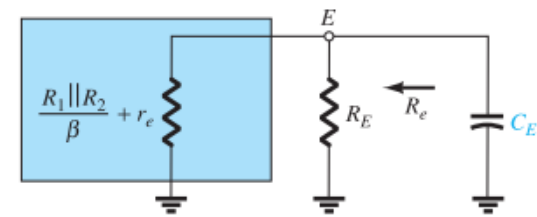


FIG. 9.30

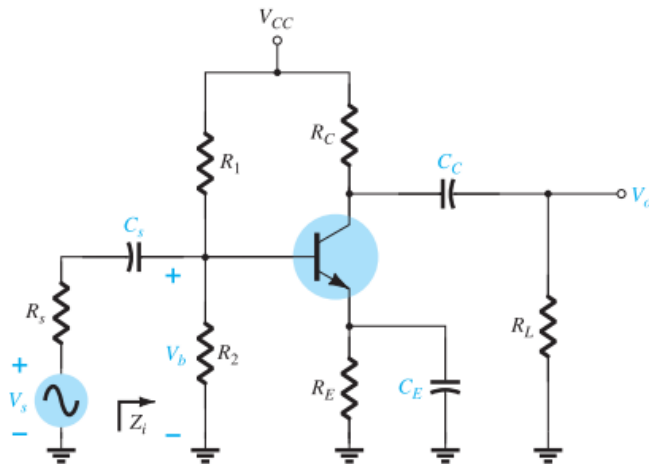
Localized ac equivalent of  $C_E$ .



# IMPACT OF $R_S$ ON THE BJT LOW FREQUENCY RESPONSE

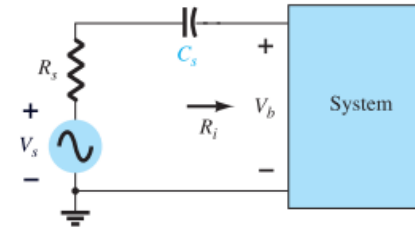


# Impact of $R_s$



**FIG. 9.32**

Determining the effect of  $R_s$  on the low-frequency response of a BJT amplifier.



**FIG. 9.33**

Determining the effect of  $C_s$  on the low-frequency response.

$$f_{L_s} = \frac{1}{2\pi(R_i + R_s)C_s}$$

$$f_{L_C} = \frac{1}{2\pi(R_o + R_L)C_C}$$

$$f_{L_E} = \frac{1}{2\pi R_e C_E}$$

$$R_e = R_E \parallel \left( \frac{R'_s}{\beta} + r_e \right) \text{ and } R'_s = R_s \parallel R_1 \parallel R_2$$

# Example

## EXAMPLE 9.12

- Repeat the analysis of Example 9.11 but with a source resistance  $R_s$  of 1 k $\Omega$ . The gain of interest will now be  $V_o/V_s$  rather than  $V_o/V_i$ . Compare results.
- Sketch the frequency response using a Bode plot.
- Verify the results using PSpice.

**Solution:** a. The dc conditions remain the same:

$$r_e = 15.76 \Omega \text{ and } \beta r_e = 1.576 \text{ k}\Omega$$

**Midband Gain**  $A_v = \frac{V_o}{V_i} = \frac{-R_C \parallel R_L}{r_e} \cong -90$  as before

The input impedance is given by

$$\begin{aligned} Z_i = R_i = R_1 \parallel R_2 \parallel \beta r_e \\ = 40 \text{ k}\Omega \parallel 10 \text{ k}\Omega \parallel 1.576 \text{ k}\Omega \\ \cong 1.32 \text{ k}\Omega \end{aligned}$$

and from Fig. 9.35,

$$V_b = \frac{R_i V_s}{R_i + R_s}$$

or

$$\frac{V_b}{V_s} = \frac{R_i}{R_i + R_s} = \frac{1.32 \text{ k}\Omega}{1.32 \text{ k}\Omega + 1 \text{ k}\Omega} = 0.569$$

so that

$$\begin{aligned} A_{v_s} = \frac{V_o}{V_s} &= \frac{V_o}{V_i} \cdot \frac{V_b}{V_s} = (-90)(0.569) \\ &= -51.21 \end{aligned}$$

**C<sub>s</sub>**

$$R_i = R_1 \parallel R_2 \parallel \beta r_e = 40 \text{ k}\Omega \parallel 10 \text{ k}\Omega \parallel 1.576 \text{ k}\Omega \cong 1.32 \text{ k}\Omega$$

$$\begin{aligned} f_{L_s} &= \frac{1}{2\pi(R_s + R_i)C_s} = \frac{1}{(6.28)(1 \text{ k}\Omega + 1.32 \text{ k}\Omega)(10 \mu\text{F})} \\ f_{L_s} &\cong 6.86 \text{ Hz vs. } 12.06 \text{ Hz without } R_s \end{aligned}$$

**C<sub>C</sub>**

$$\begin{aligned} f_{L_C} &= \frac{1}{2\pi(R_C + R_L)C_C} \\ &= \frac{1}{(6.28)(4 \text{ k}\Omega + 2.2 \text{ k}\Omega)(1 \mu\text{F})} \\ &\cong 25.68 \text{ Hz as before} \end{aligned}$$

**C<sub>E</sub>**

$$\begin{aligned} R'_s &= R_s \parallel R_1 \parallel R_2 = 1 \text{ k}\Omega \parallel 40 \text{ k}\Omega \parallel 10 \text{ k}\Omega \cong 0.889 \text{ k}\Omega \\ R_e &= R_E \parallel \left( \frac{R'_s}{\beta} + r_e \right) = 2 \text{ k}\Omega \parallel \left( \frac{0.889 \text{ k}\Omega}{100} + 15.76 \Omega \right) \\ &= 2 \text{ k}\Omega \parallel (8.89 \Omega + 15.76 \Omega) = 2 \text{ k}\Omega \parallel 24.65 \Omega \cong 24.35 \Omega \\ f_{L_E} &= \frac{1}{2\pi R_e C_E} = \frac{1}{(6.28)(24.35 \Omega)(20 \mu\text{F})} = \frac{10^6}{3058.36} \\ &\cong 327 \text{ Hz vs. } 87.13 \text{ Hz without } R_s. \end{aligned}$$

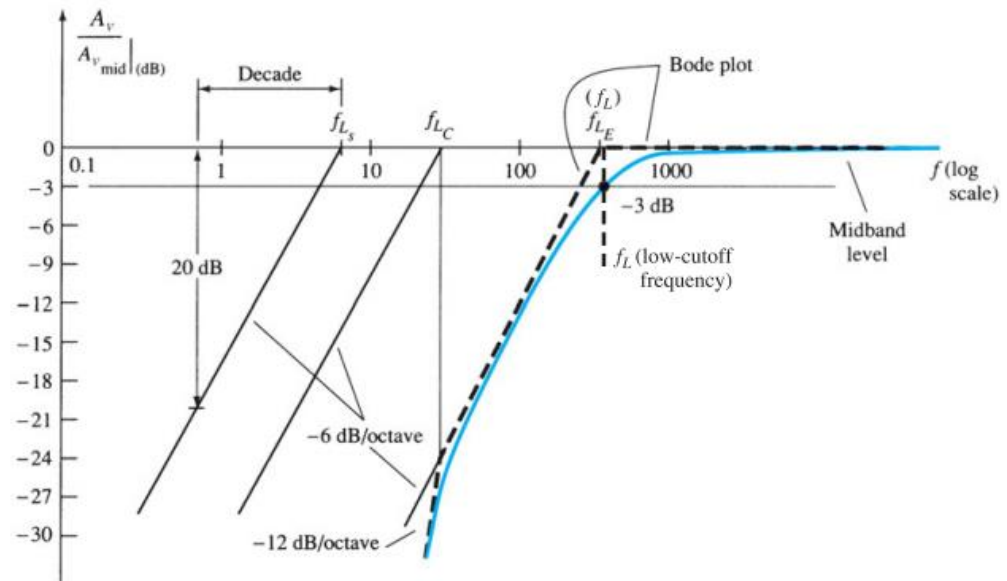


FIG. 9.36

Low-frequency plot for the network of Example 9.12.



- For more details, refer to:
  - Chapter 9 at R. Boylestad, **Electronic Devices and Circuit Theory**, 11<sup>th</sup> edition, Prentice Hall.
- The lecture is available online at:
  - <http://bu.edu.eg/staff/ahmad.elbanna-courses/11966>
- For inquires, send to:
  - [ahmad.elbanna@feng.bu.edu.eg](mailto:ahmad.elbanna@feng.bu.edu.eg)